Race to the Finish

Challenge Description
Use feedback from the Remote Control to race through a teacher designed course as quickly as possible. Use a stopwatch to record your time and compare it to your competition.

Sample Code
The sample program below assigns the value of the VEX Joysticks to the appropriate motors.

```c
#pragma config(Motor, port2, rightMotor, tmotorNormal, openLoop, reversed)
#pragma config(Motor, port3, leftMotor, tmotorNormal, openLoop)
//!*!Code automatically generated by ‘ROBOTC’ configuration wizard !*/

task main()
{
    while(1 == 1) //while one equals one, which is forever
    {
        motor[leftMotor] = vexRT[Ch3]; //set the value of motor port 3 to the
                                      //value of channel 3 on the remote control
        motor[rightMotor] = vexRT[Ch2]; //set the value of motor port 2 to the
                                         //value of channel 2 on the remote control
    }
}
```