**Wall Detection (Touch) Quiz**

1. The recommended method of configuring sensors in ROBOTC is to use the Motors and Sensors Setup menu shown above.
   a. True
   b. False

2. What form does feedback from the Touch Sensor take?
   a. A number between 0 and 255, indicating how hard the button is being pressed.
   b. A number, either 0 or 1, indicating Pressed or Not Pressed.
   c. Pounds per square inch of pressure.
   d. A or B, depending on how the user configures the sensor.

3. In plain English (or pseudocode), describe what the following code does.

   ```plaintext
   while(SensorValue(touchSensor) == 1)
   {
   motor[motorC] = 100;
   motor[motorB] = 0;
   }
   ```

4. In general, when does a while loop run the body of its code?
   a. When its condition is true.
   b. When its condition is false.
   c. When the sensor gives feedback above the value of threshold.
   d. If the motor has been given a power level and assigned a wait state in milliseconds.